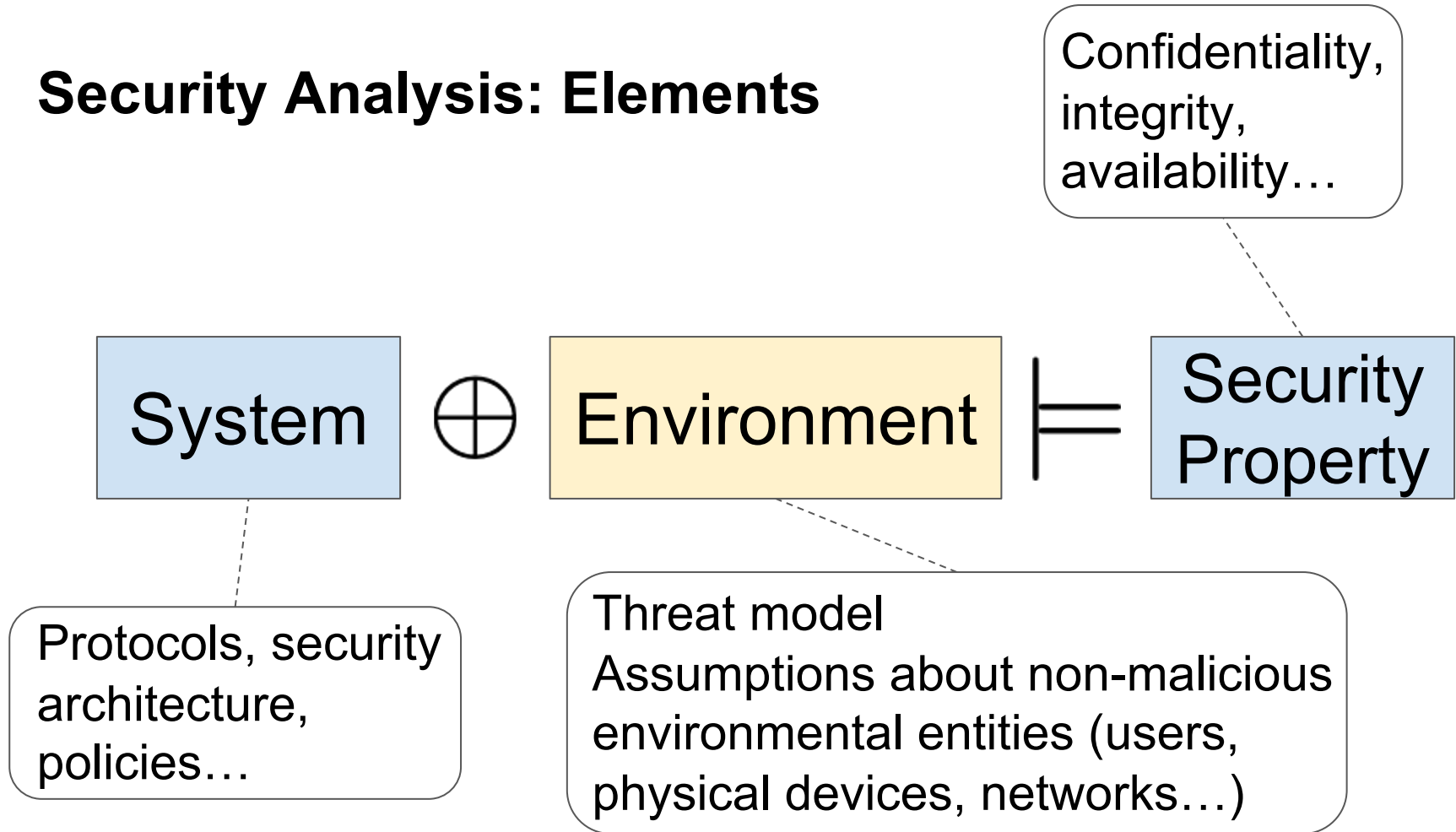


# Reasoning about the Robustness of Protocols

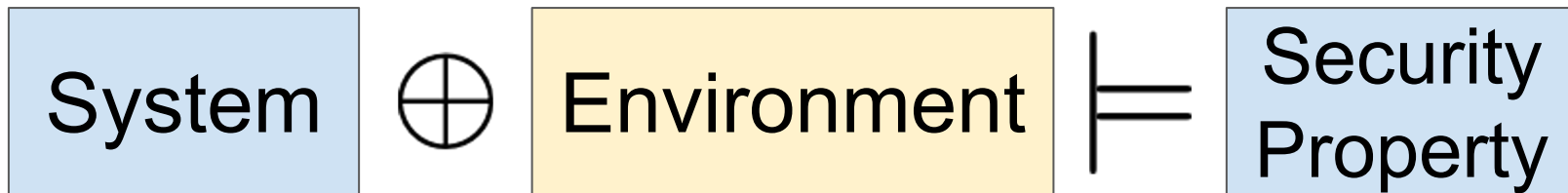
Eunsuk Kang

High Confidence Software & Systems Conference  
May 9, 2023

# Security Analysis: Elements

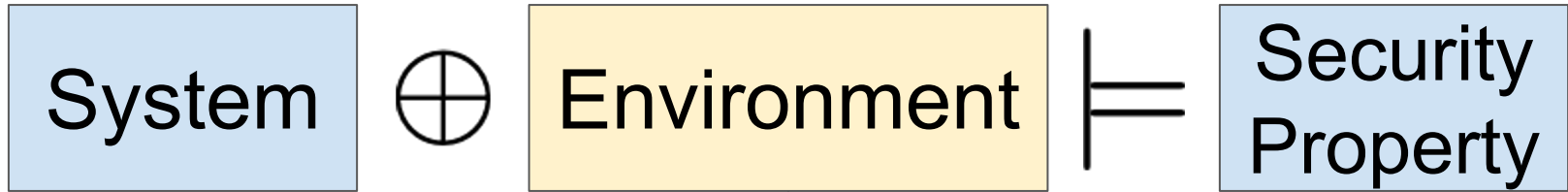


## Security Analysis: Goal



*Does the system, when deployed under the **assumed** environment, satisfy the property?*

# Security Analysis: Challenges



1. How do we know what assumptions we are making?
2. What if our assumptions turn out to be wrong/broken?

# Example: E-Voting Attack (ES&S iVotronic)



FRANKFORT — A former Clay County precinct worker testified Friday that top election officers in the county taught her how to change people's choices on voting machines to steal votes in the May 2006 primary.

Voters walk away from the machine before pressing “confirm”  
Election officials enter booth, press “back” & modify the vote

# Example: E-Voting Attack



**Assumed** user behavior: Complete the voting process with “confirm”  
But in practice, this assumption may sometimes fail to hold!

Alternative designs might mitigate this issue:  
e.g., timeout after no response, require PIN after confirm

# Problem

Once a system is deployed, its actual environment may **deviate** from the assumed one, possibly undermining the security property.

Can we design systems that are **robust** – providing security even under the presence of such deviations?

Can we provide tools to aid developers in this process?

# Robust-by-Design Systems

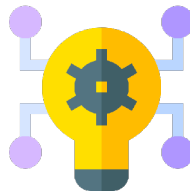
## Specification

What does it mean for our system to be robust?



## Analysis

How robust is our system?



## Robustification

How do we improve its robustness?



# Robust-by-Design Systems

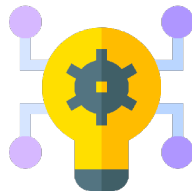
## Specification

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## Robustness: Formal Definition

$$M \parallel E \models P$$



$\Delta$

Deviations

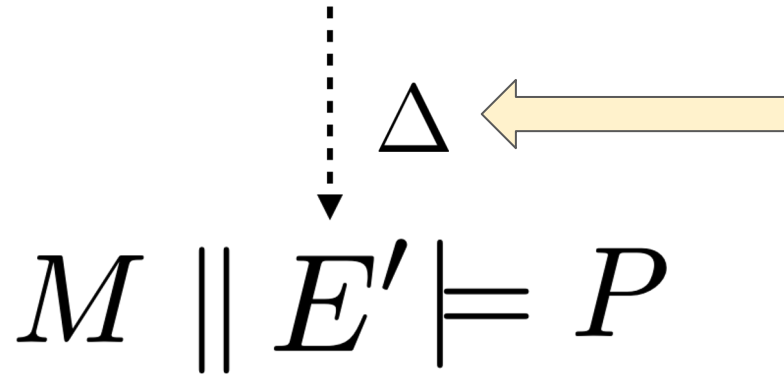
$$M \parallel E' \models P$$

Deviated environment

System (M) is **robust** against a set of deviations ( $\Delta$ ) with respect to environment (E) and security property (P)

## Robustness: Formal Definition

$$M \parallel E \models P$$



The diagram illustrates a deviation Δ from environment E to environment E'. A dashed vertical arrow points from E down to E', and a yellow arrow points from a box of examples to the deviation symbol Δ.

$$M \parallel E' \models P$$

### Examples:

User errors (e.g., omit a critical action)

Network failures

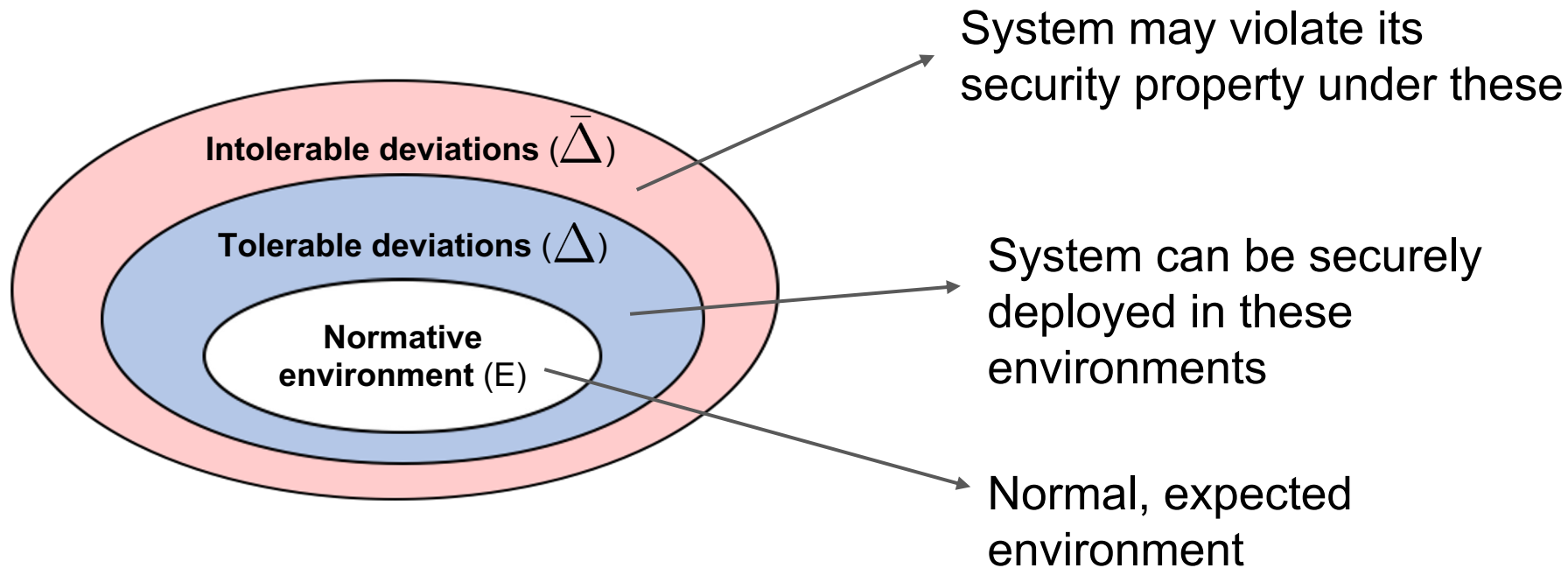
Sensor noise

Changes in attacker knowledge/capabilities

...

System (M) is **robust** against a set of deviations ( $\Delta$ ) with respect to environment (E) and security property (P)

# Robustness: Another View



**Overall robustness** = maximal  $\Delta$  set

Larger  $\Delta \Rightarrow$  more robust system!

# Automata-Theoretic Definition

Transition  
systems

Logical  
specification

$$M \parallel E \models P$$

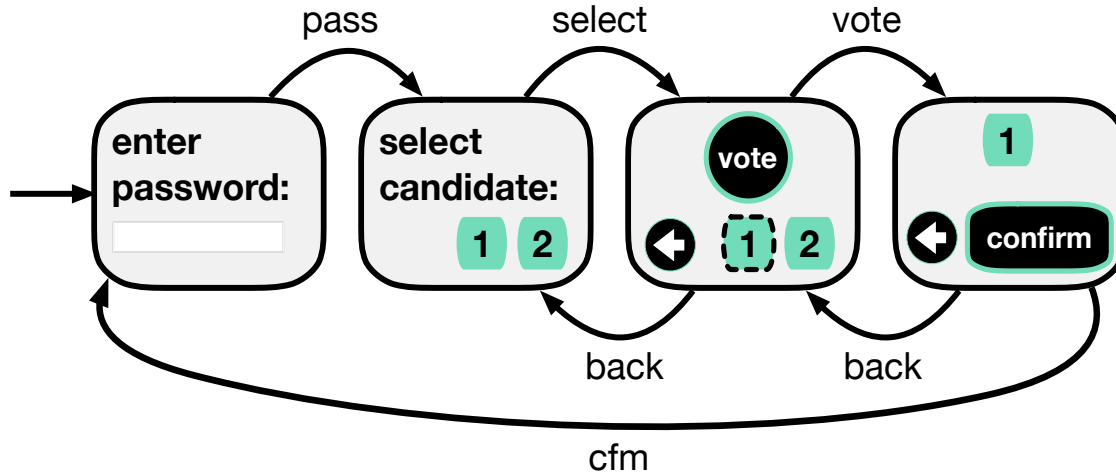


Additional traces  
(i.e., behaviors)

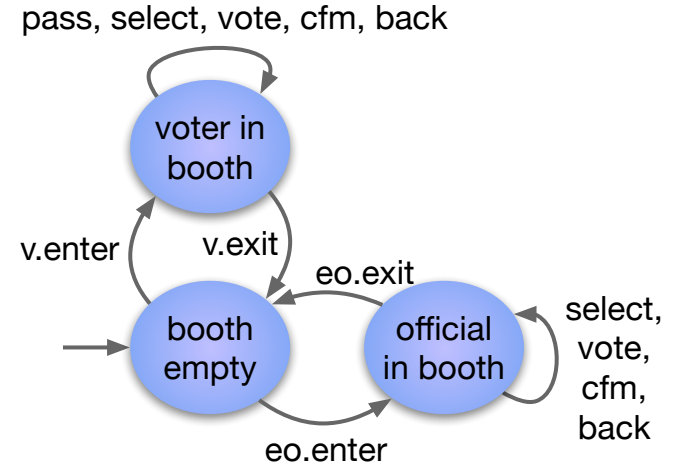
$$M \parallel E' \models P$$

E with additional  
behaviors

# Example: Voting Machine as Transition Systems



**Voting Interface**

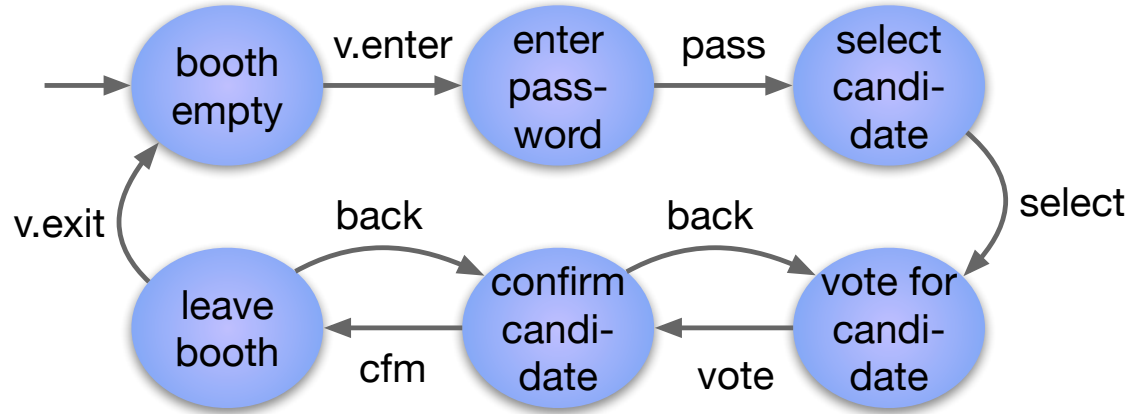


**Booth**

**System (M) = Voting Interface || Booth**

# Voting Machine as Transition Systems

**Environment (E)**  
i.e., expected voter  
behavior

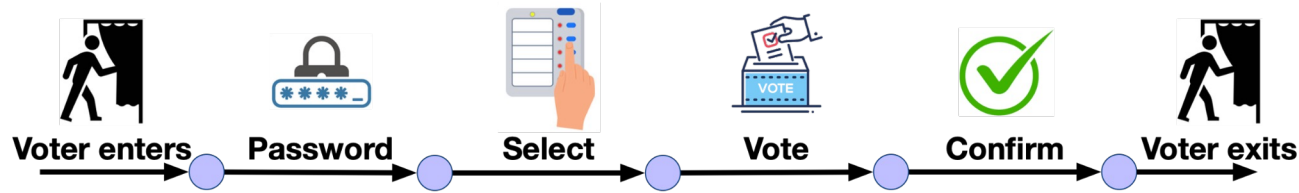


**Security**  
**Property (P)**

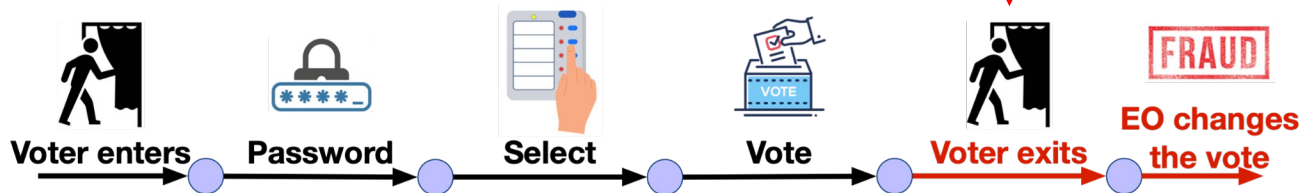
*“No user can change the vote made by  
another person”*  
(in a logical specification)

# Deviation as an Additional Trace

Expected voter behavior (trace of E)



Possible intolerable deviation ( $\bar{\Delta}$ )



**Security Violation!**



# Automata-Theoretic Definition

Transition  
systems

Logical  
specification

$$M \parallel E \models P$$



Additional traces  
(i.e., behaviors)

$$M \parallel E' \models P$$

E with additional  
behaviors

## Key idea

Given  $M$  &  $E$  as state machines, we can compute deviations (i.e.,  $\Delta$  &  $\bar{\Delta}$ ) as a measure of robustness

# Robust-by-Design Systems

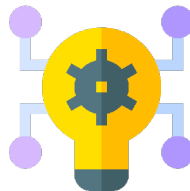
## Specification

What does it mean for our system to be robust?



## Analysis

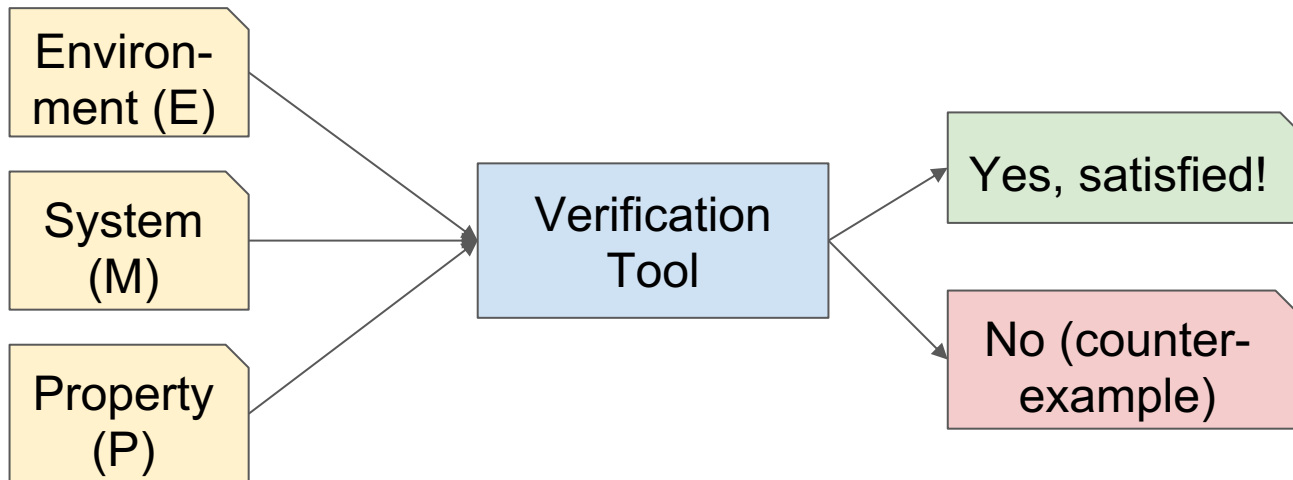
How robust is our system?



## Robustification

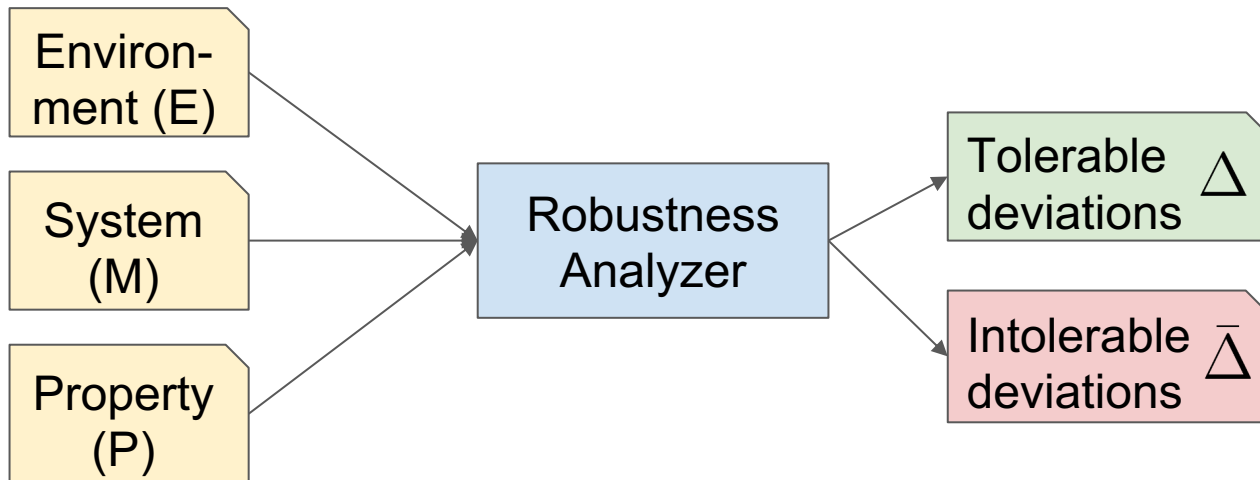
How do we improve its robustness?

# Standard Verification Problem



Given  $M$ ,  $E$ ,  $P$ , does the system satisfy the property?

# Robustness Analysis

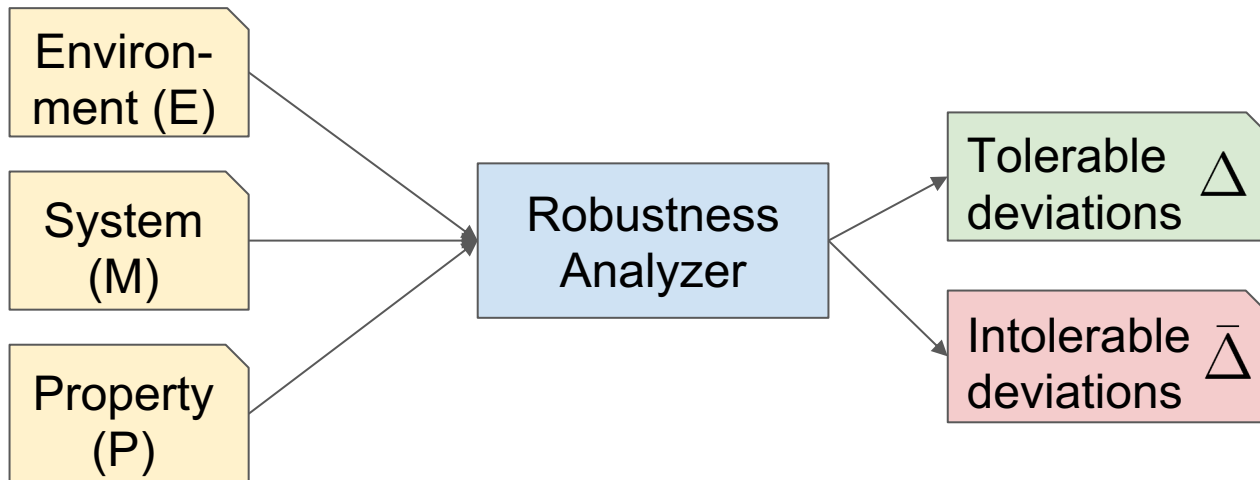


## Robustness Analysis

Given  $M$ ,  $E$ ,  $P$ , how robust is the system ( $\Delta$ )?

What are deviations that it cannot tolerate ( $\bar{\Delta}$ )?

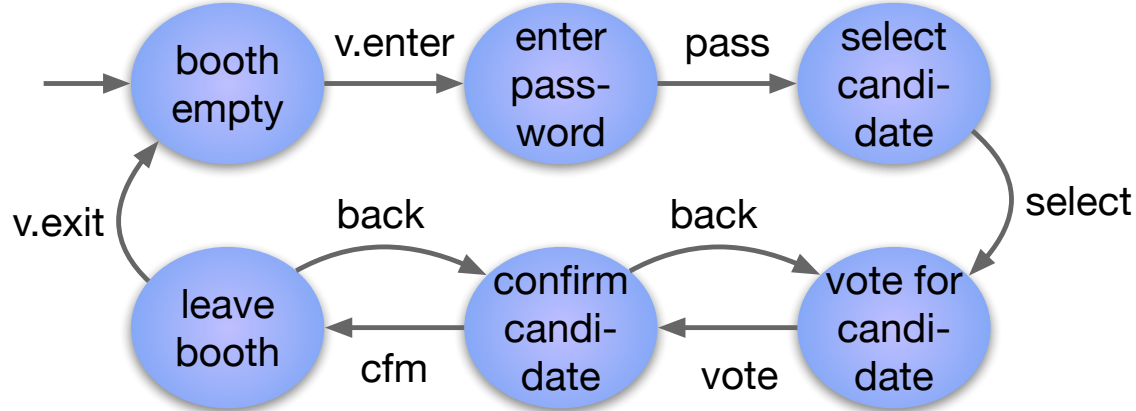
# Robustness Analysis



## Technical challenges:

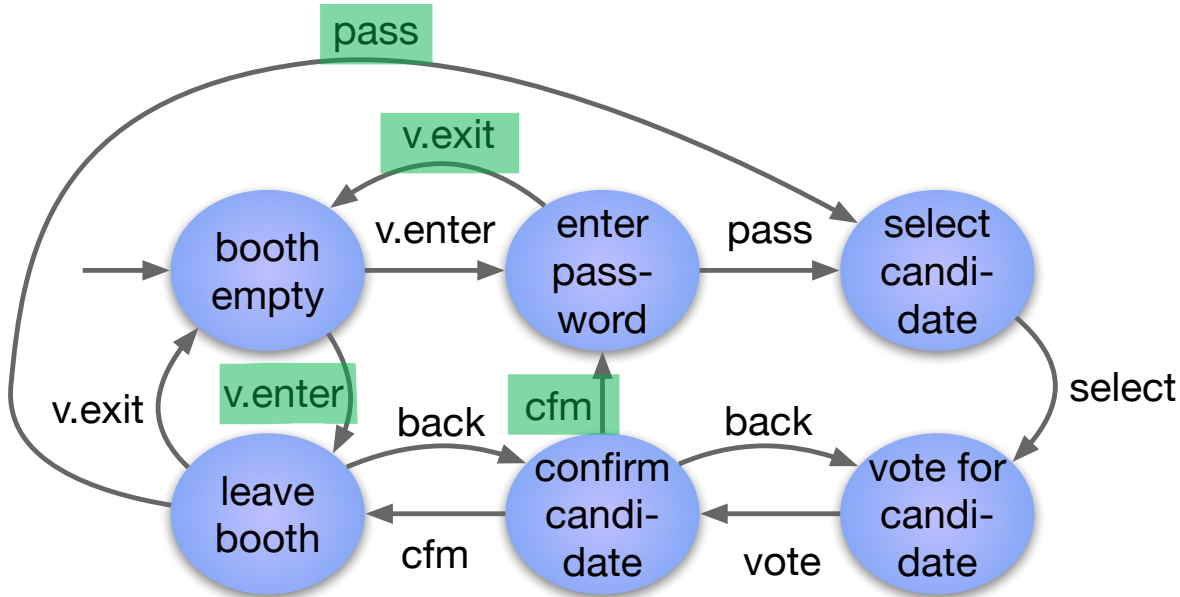
1. Computing the set of all deviations efficiently
2. Representing  $\Delta$  concisely for comprehension

# Example: Computing Deviations in Voter Behavior



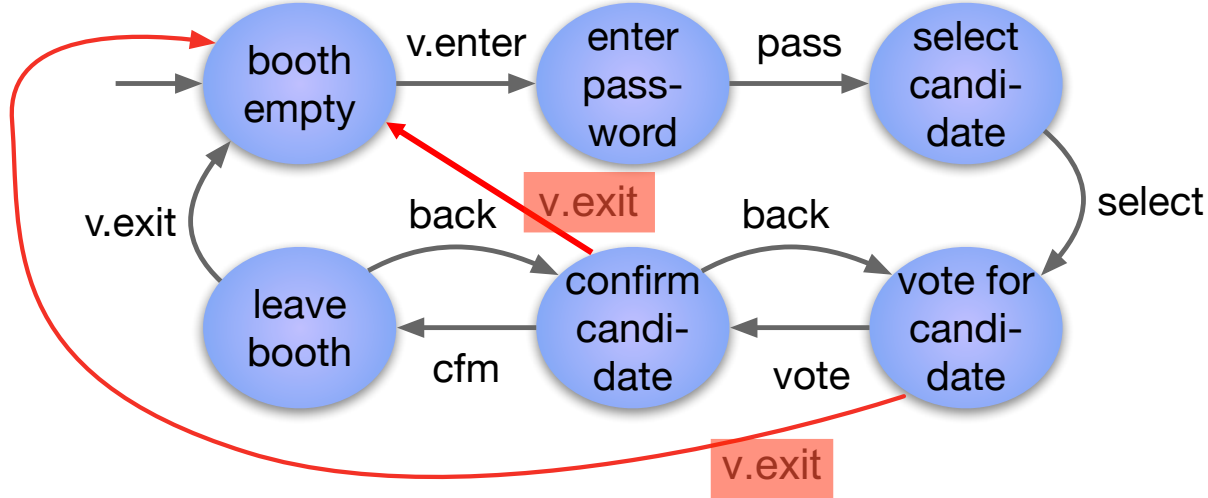
**Environment (E): Assumed voter behavior**

## Example: Tolerable Deviations ( $\Delta$ )



Represented as **added transitions** to E  
System **preserves** its property under these deviations

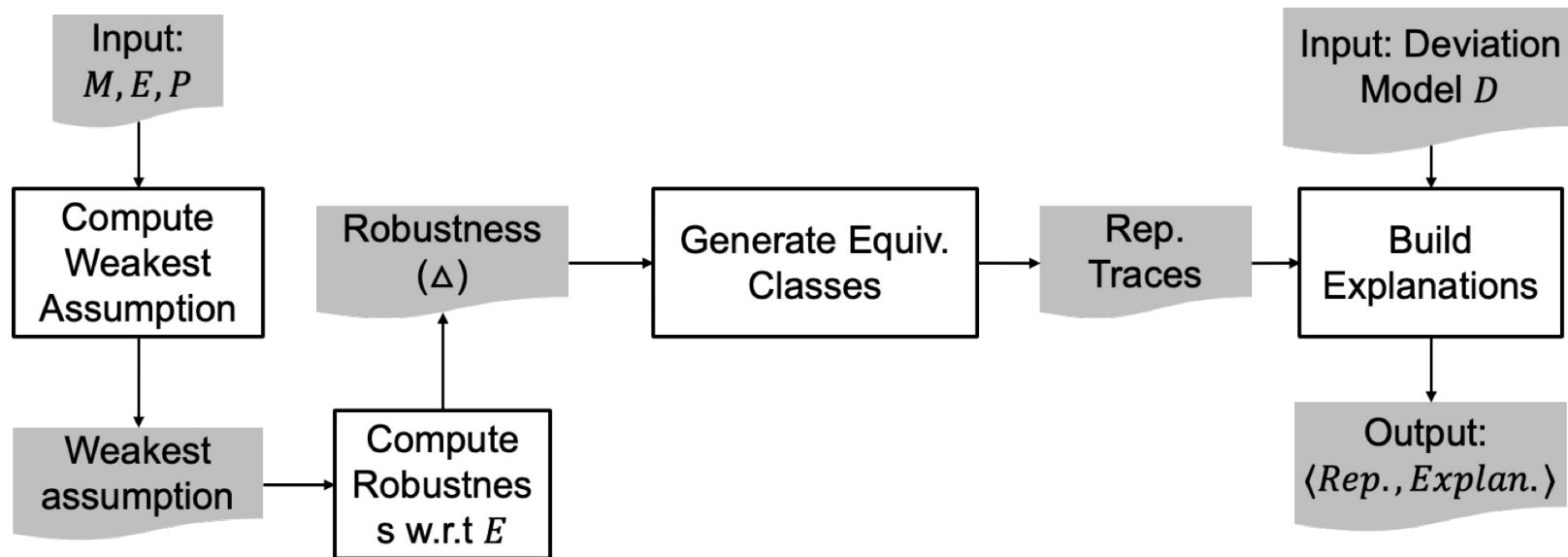
## Example: Intolerable Deviations ( $\bar{\Delta}$ )



System may **violate** its property under these deviations!



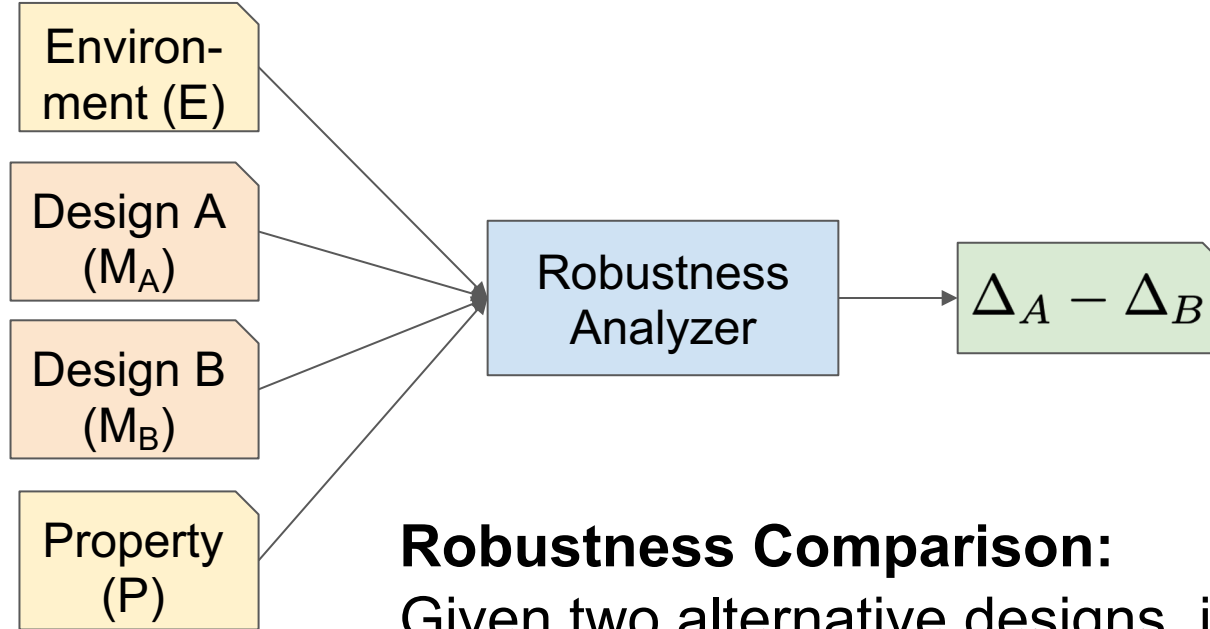
# Analysis Process



**More details in our paper!**

*A behavioral notion of robustness for software systems.  
Zhang, Garlan, and Kang. ESEC/FSE 2020.*

# Comparing Designs w.r.t. Robustness



## Robustness Comparison:

Given two alternative designs, is one more robust than the other (and if so, under what deviations)?

# Robust-by-Design Systems

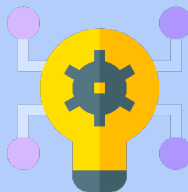
## Specification

What does it mean for our system to be robust?



## Analysis

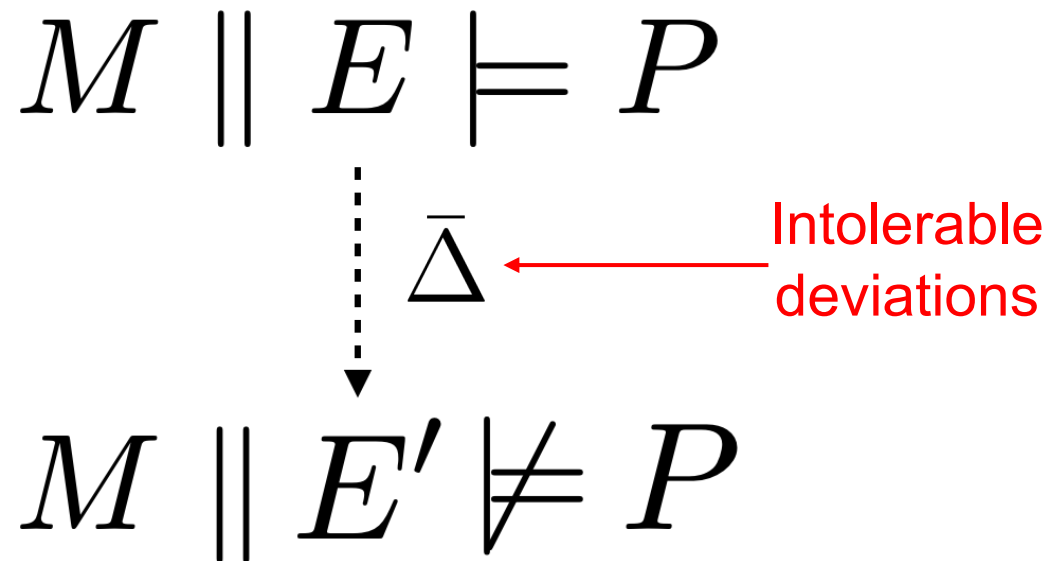
How robust is our system?



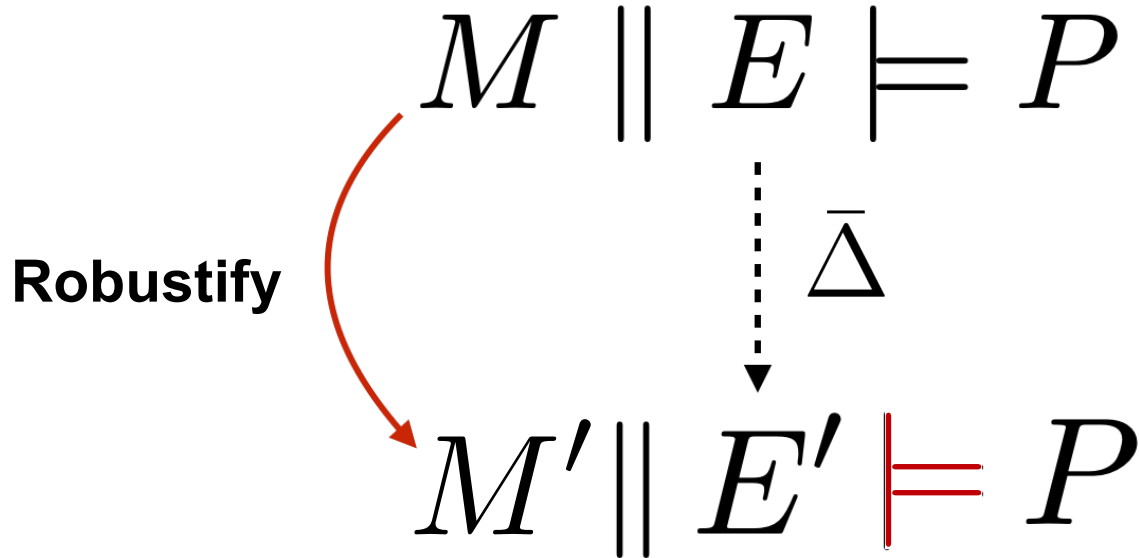
## Robustification

How do we improve its robustness?

# Robustification

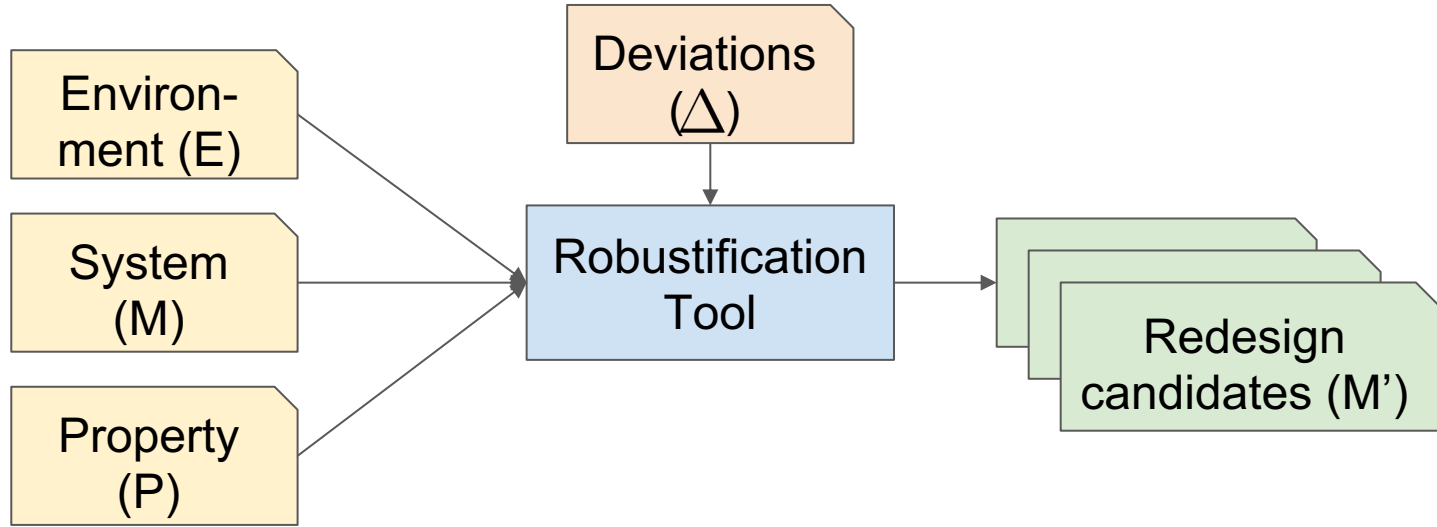


# Robustification



*Can we generate suggestions for enhancing the original design to tolerate additional deviations?*

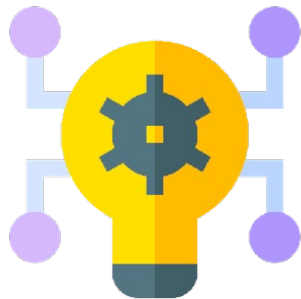
# Robustification



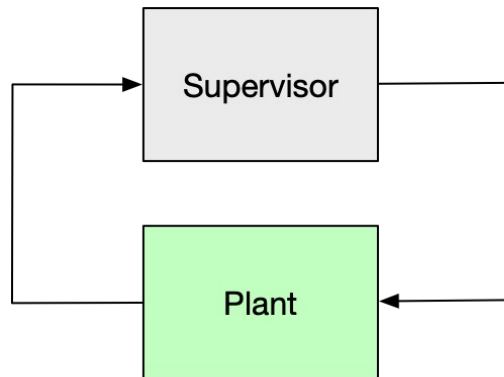
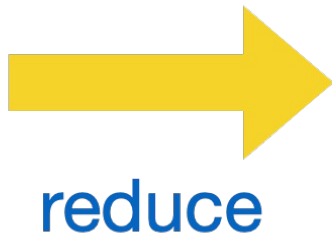
## Technical challenges:

1. Searching a large space of candidate solutions
2. Trade-offs between permissiveness vs. complexity

# Robustification as Supervisory Control Synthesis

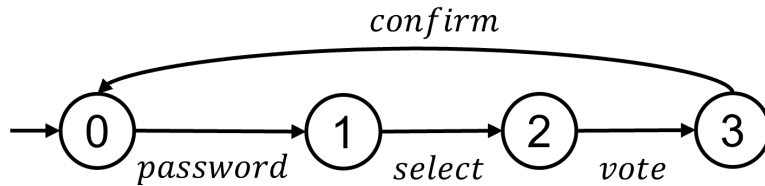


Robustification  
problem



Supervisory  
control problem

# Candidate Solutions

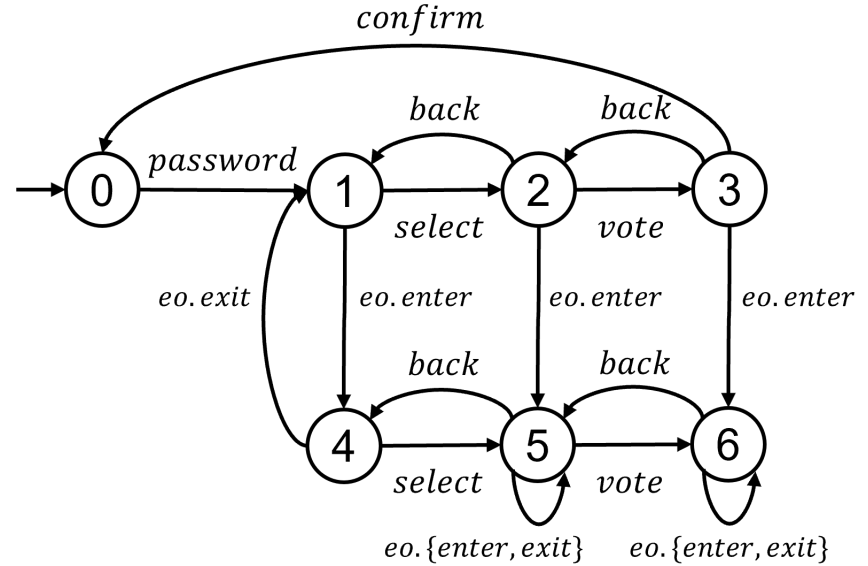


## Redesign #1

Disables “back” action

Simple, but **not permissive**

Does not allow voter to modify selection



## Redesign #2

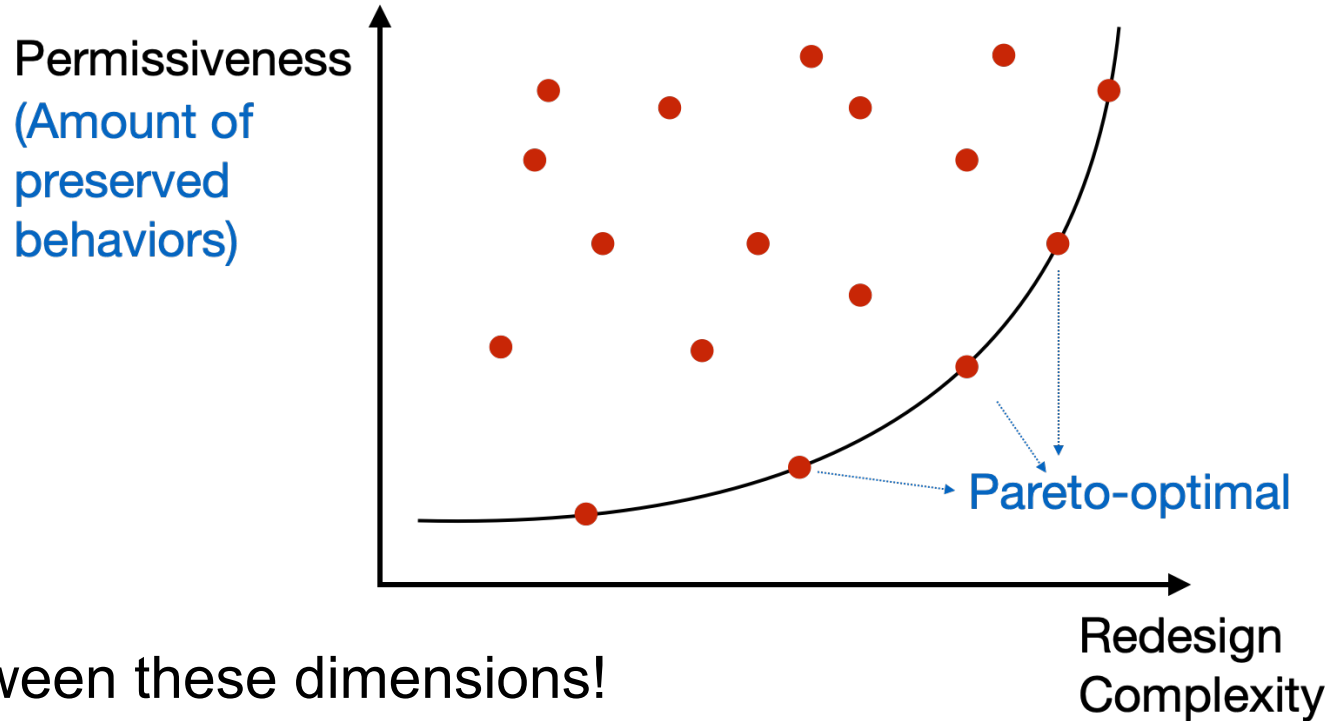
Disables confirm while the official is in the booth

More **permissive**: Allows vote change

But **more complex**: Requires keeping track of booth occupant



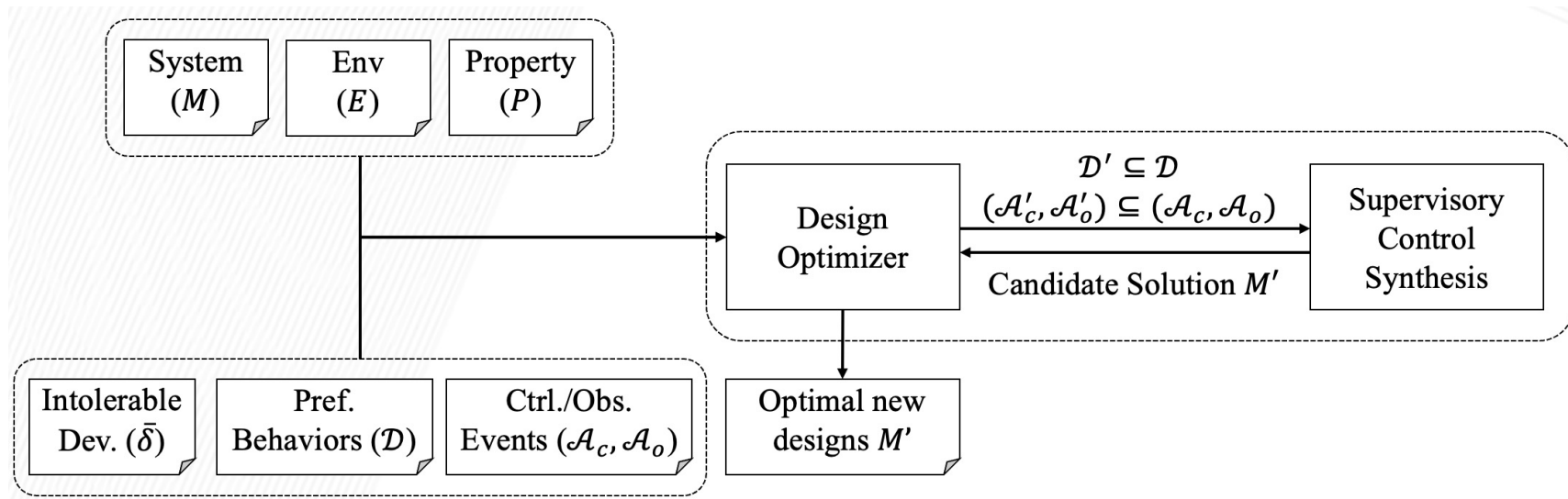
# Optimal Robustification



Trade-offs between these dimensions!

Generate multiple possible Pareto-optimal solutions

# Robustification Process



**More details in our paper!**

*Robustification of Behavioral Designs against  
Environmental Deviations. Zhang et al. ICSE 2023.*

# Case Studies



OAuth authorization protocols



Oyster Card protocol



Medical device interfaces  
(radiation therapy,  
infusion pumps)

Largest model size: ~19k states  
Robustness analysis: < 2.0 seconds  
Robustification: ~8 minutes

# Takeaway

**Robustness:** What potential deviations can my system tolerate & achieve a desired security goal?

With robustness as a **first-class property of systems**, we can:

- > Reason about the impact of deviations on security
- > Compare alternative designs w.r.t. robustness
- > Design systems to achieve a desired level of robustness

Try our tool!

<https://github.com/cmu-soda/Fortis>